



Integrating Site Monitoring and Ergonomics into Smart Construction

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Content

1. Automated site management based on IoT, Smart Insole and Computer Vision

- 2. Establishing traceability chain for quality management based on tool tracking
- 3. Integrating ergonomics with smart construction

4. Future Plan





- > Management focuses on reactive/remedial actions
- > Increasing 'management cost';



1. Automated site management based on IoT, Smart Insole and Computer Vision

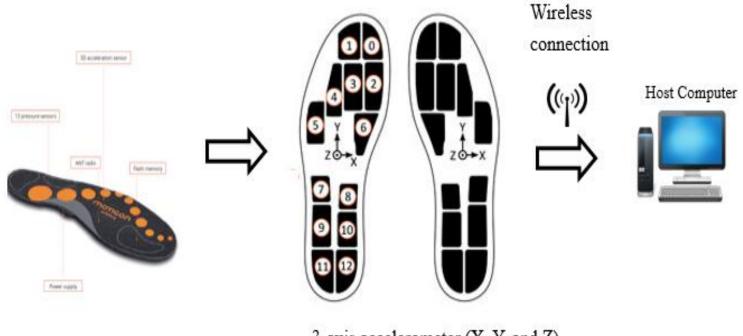


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Location-based Technologies for Real-time Site Safety Management System 應用於工地的 實時風險警報管理系統



Smart Insole



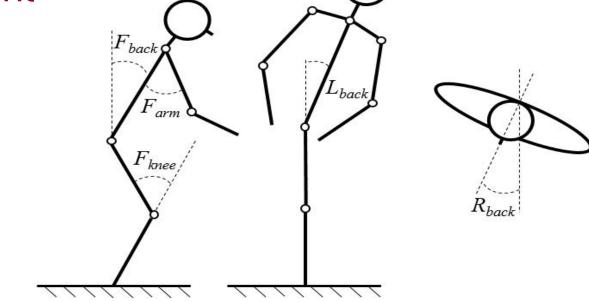
3-axis accelerometer (X, Y, and Z) 13 force capacitor per insole sensor

Figure 5: Overview of Foot Plantar Pressure Sensing System





Predicting postures of workers from inverse dyna

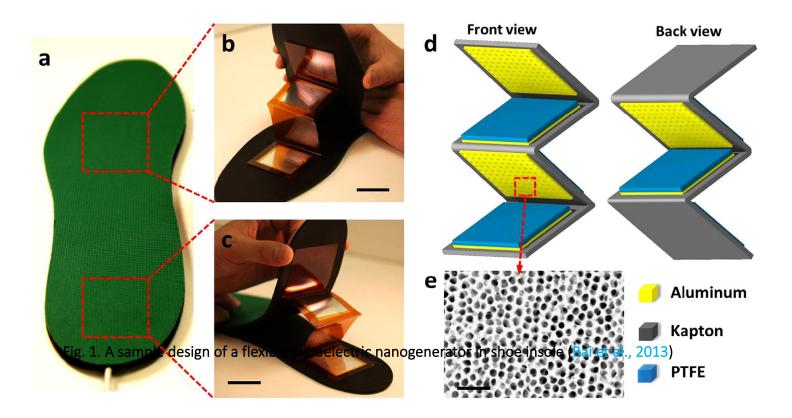




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Self-power system





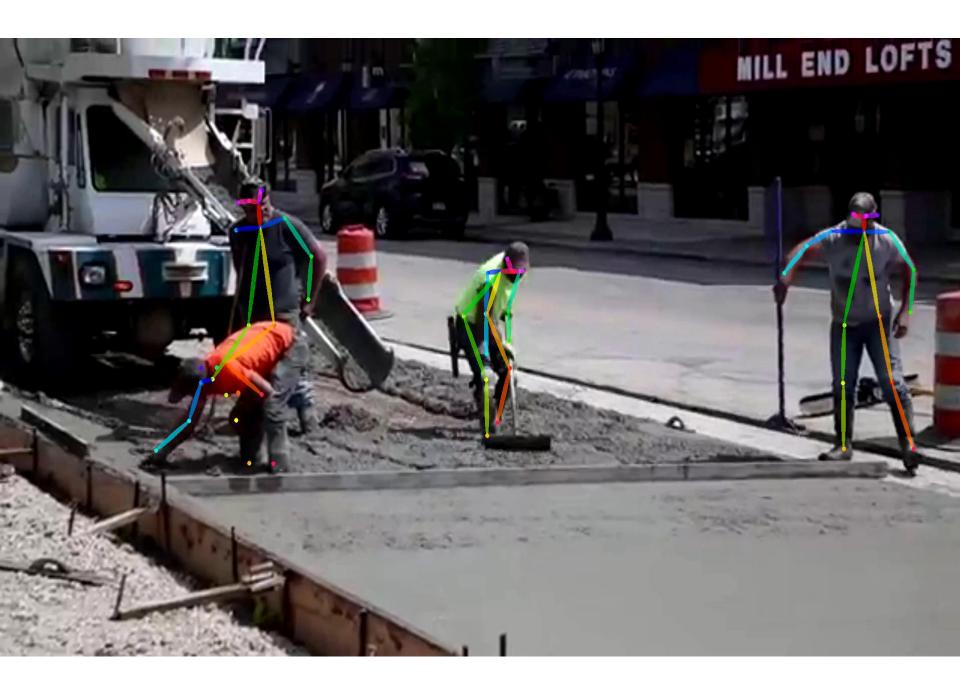


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Computer vision and deep learning

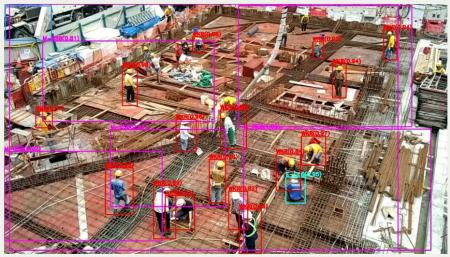


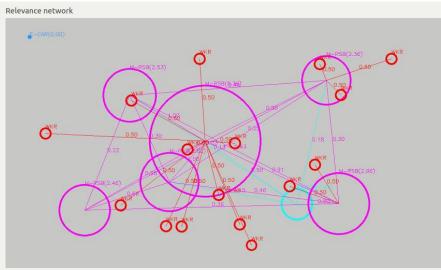


From recognizing action to recognizing activity, to productivity



Visual detection

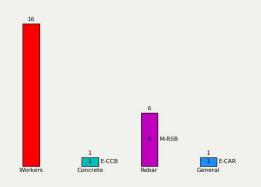




Summary

ONGOING ACTIVITIES:

1): 16 worker(s) involved in fixing, erecting, or treating rebar



Analysis in progress



2. Establishing traceability chain for quality management based on tool tracking





A reliable way to record- Traceability

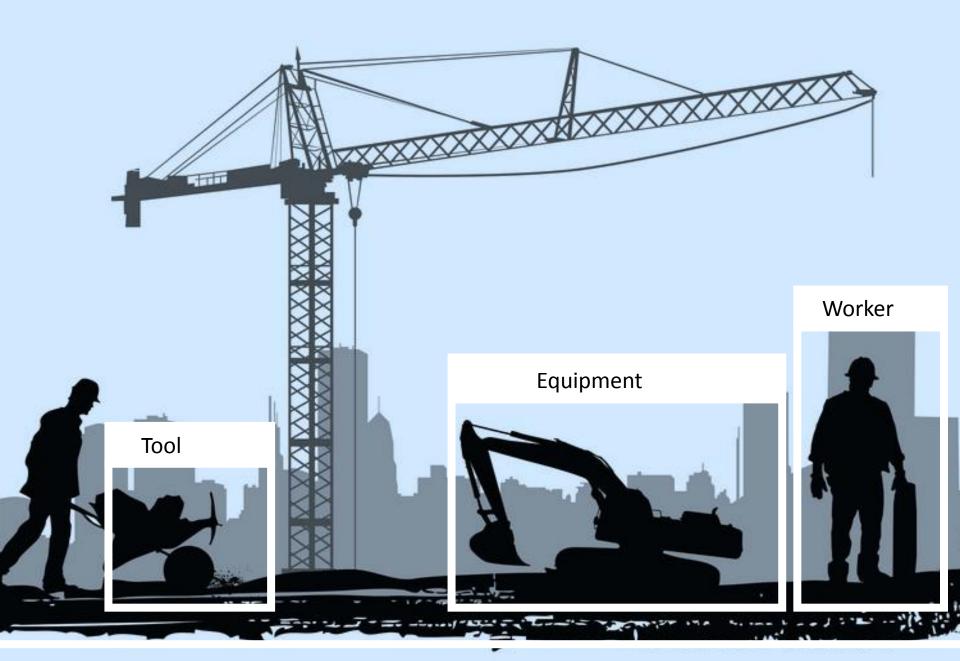


By X.Y.



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Construction Site





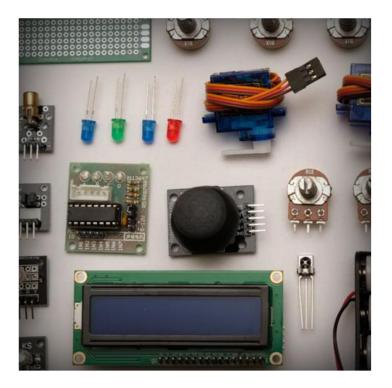




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Hardware





System Inertial Measurement Unit

Bluetooth Low Energy 4.2

- Communication 4.2 Mbits / s
- Distance 50 m

By X.Y.



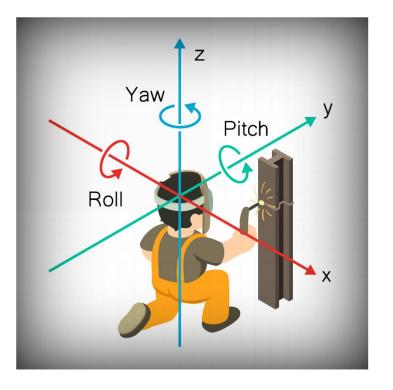
IMU based tracking

system



7件 语言	帮助										
空制	时间		实时计算	实时绘制	详细设置						
设置	实际时间	ĺ	校准模	ت ڑ							
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校准清零											
]加速度	加速度		零偏设	置							
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速度	y轴:	m / s2	×轴:	0.00	m / s2	x轴:	0.00	deg / s	x轴:	0.00	mG
地磁强度	z 轴:	m / s2	y 轴:	0.00	<mark>m /</mark> s2	y 轴:	0.00	deg / s	y 轴:	0.00	mG
	角速度		z轴:	9.80	m / s2	z 轴:	0.00	deg / s	z 轴:	0.00	mG
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	z 轴:	deg / s	回传设								
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	z轴:	deg									
	地磁强度		其他设	置							
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	y 轴:	mG			Æ						
	z轴:	mG									





$$\phi = \tan^{-1} \frac{a_y}{a_z}$$

$$\theta = \tan^{-1} \frac{-a_x}{\sqrt{a_x^2 + a_y^2}}$$

$$= \tan^{-1} \frac{-m_x^N}{m_y^N} \pm \Delta \psi$$

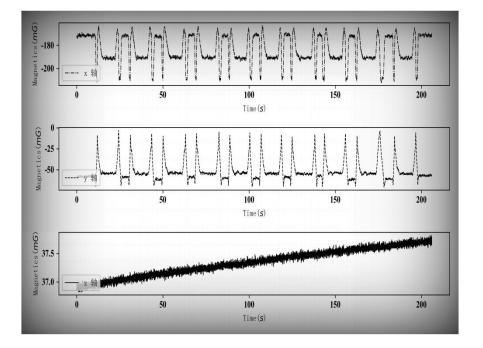
$$= \tan^{-1} \frac{-\cos\phi m_y^B + \sin\phi m_z^B}{\cos\theta m_z^B + \sin\phi \sin\theta m_y^B + \cos\phi \sin\theta m_z^B} \pm \Delta \psi$$

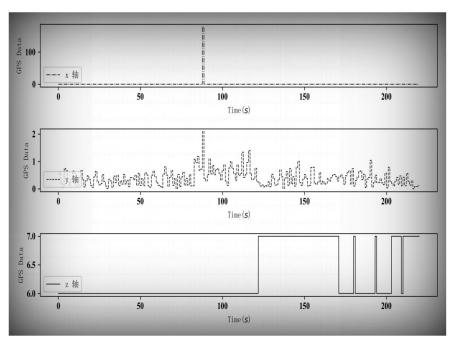
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By X.Y.







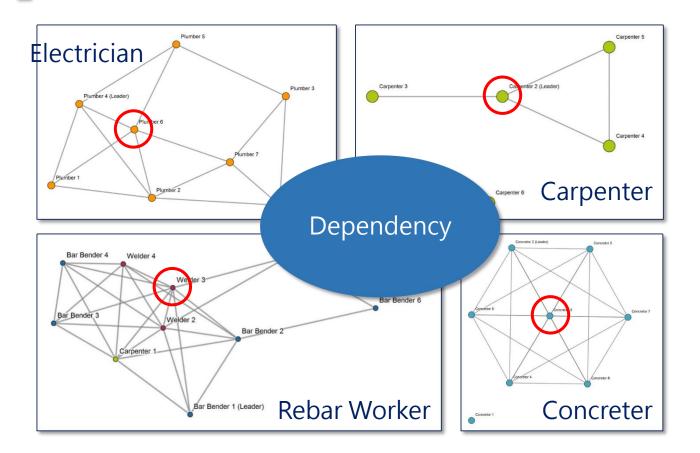


By X.Y.





Dependence network

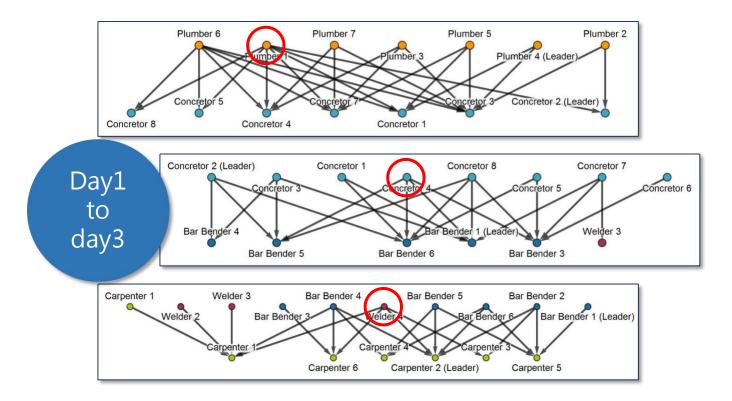




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Sequential inter-dependency netweork



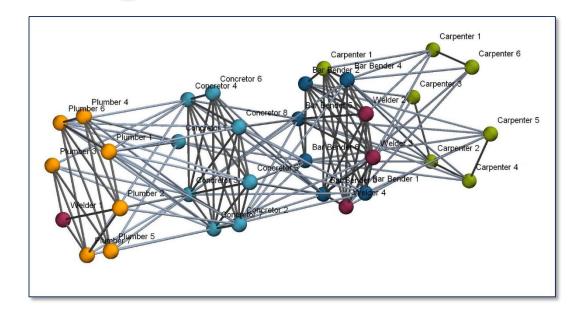


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Traceability chain



It is possible to develop a traceability chain using the dependency network. This allows to trace "who should be responsible for it, if something goes wrong"

HOW IS A PLANE TRACKED?

On board are cockpit voice and flight data recorders – the 'black boxes' – which each include a 'pinger' that sends a transmission up to 30 days after submersion.

In the black box was an ASD-B flight transponder which, unlike the GPS in a car, broadcasts its location by sending information back to air traffic controllers every second.

Crews are able to speak to their airline through discrete radio channels. The aircraft was comfortably at a stage of flight when the pilot would have had plenty of time to report any mechanical problems to Air Traffic Control.

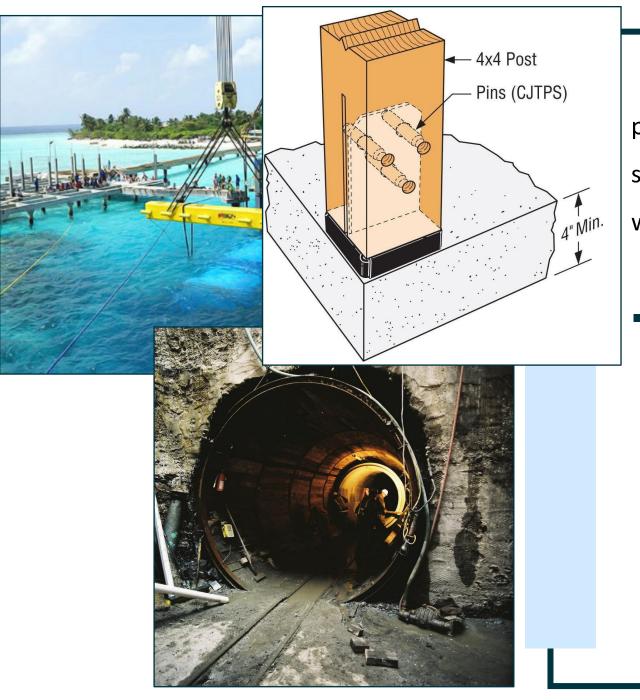
Black boxes on commercial aircraft also contain cockpit voice recorders which could provide some insight into what went wrong on that plane at 1am on Friday morning.

> Flight Data Recorder Records more than 100 hours of data. An insulated armoured steel housing protects the unit from impact, fire and sea water

> > ENREGISTREUR DE VOL NEPAS OUVRIR

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This technology is potentially useful in situations where portions of work are invisible.



3. Integrating ergonomics with smart construction







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Research background

Construction workers are faced with high workloads

- Physical demanding
- Confined work space
- Prolonged duration
- Insufficient break

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Research background

0 1 2 3 4 3 6 7 7 8 9 9	O-10 Borg Kating of Perceived Exertion Scale Rest Rest Restly casy Easy Moderate Sort of hard Hard Really hard Really hard Really, really, hard		
Manual	record	Wearable sensors	Vision-based methods
	implementation ective data	 Accurate results Invasiveness 	Accurate results× Indoor only

Previous fatigue assessment methods

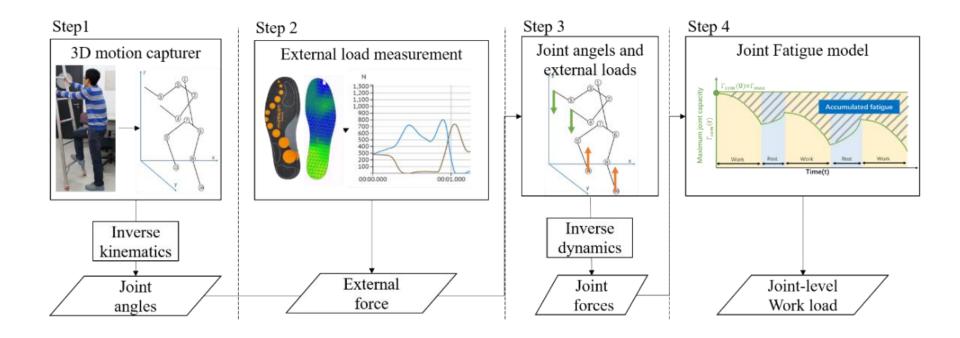


Accurate Non-invasive

Outdoor



Research method



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Research method

Task1 3D motion capture from 2D images Residual ANN

- ♦ Fully connected layer
- ♦ Increase the number of neurons in each layer

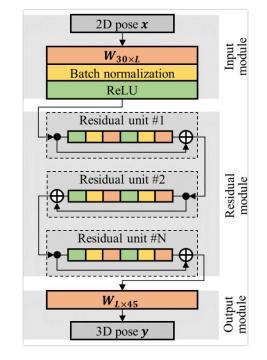
 $Y^{(l)} = Y^{(l-1)}W + b$

- Activation layer
- ♦ Increase the non-linearity of a neural network

$$g(y_{ij}) = \max(0, y_{ij})$$

- Batch-norm layer
- ♦ Improve the stability and consistency

$$\widehat{y} = \frac{y - \mu}{\sqrt{\sigma^2 + \epsilon}}$$
$$y_{BN} = \gamma \circ \widehat{y} + \beta$$

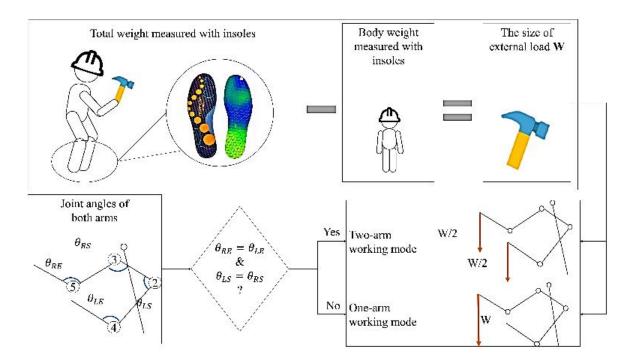


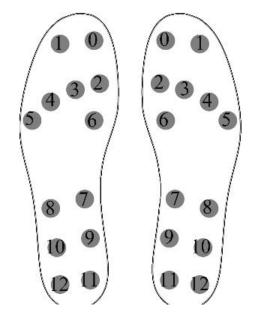
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Research method

Task 2 External load estimation with smart insoles





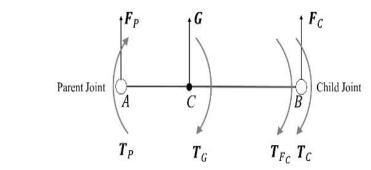
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Research method

Task 3 Joint torque calculations

Current joint torques



$$F_{Pr} + F_{Ch} + G = 0$$
$$T_{pr} + T_G + T_{F_{Ch}} + T_{Ch} = 0$$
$$T_G = \overrightarrow{AC} \times G = \overrightarrow{AB} \times G$$
$$T_{F_{Ch}} = \overrightarrow{AB} \times F_{Ch}$$

Maximum joint torque capacities

x

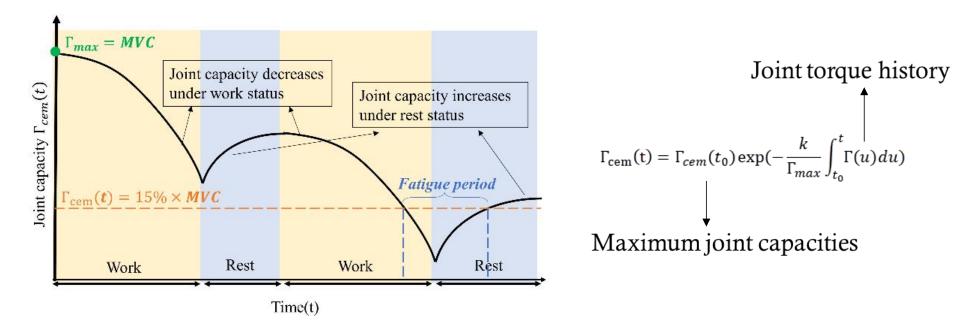
Joint capacity regression	on coefficients				
Joint	a	b	С	d	
Right shoulder	0.17	16.26	0.17	23.35	
Left shoulder	0.18	14.64	0.29	19.59	(weigh
Right elbow	0.13	11.24	0.07	22.78	$T_{max} = \left -a \cdot age + b \cdot gender + c \cdot \frac{weigh}{d} \right $
Left elbow	0.11	10.63	0.05	19.66	height
Right hip	0.33	19.19	0.66	34.44	(norgin
Left hip	0.29	18.75	0.47	36.05	
Right knee	0.16	8.78	0.08	22.47	
Left knee	0.17	7.67	0.14	21.10	





Research method

Task 4 Joint-level fatigue assessments



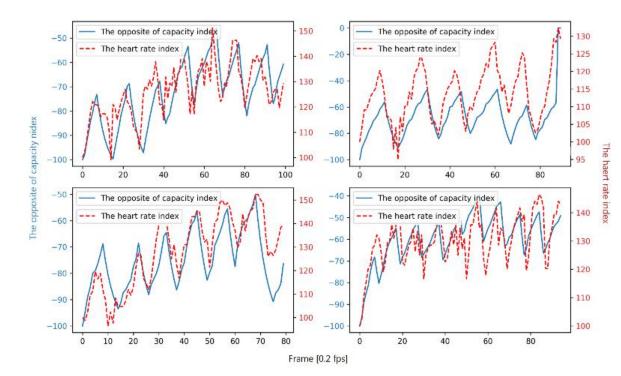
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Results and discussion

The accuracy of the fatigue assessment method

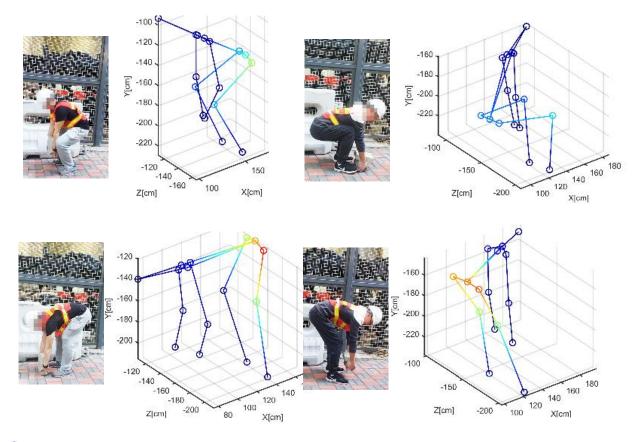
- 4 health subjects
- Heart rate monitor (Equivital[™] LifeMonitor, UK)
- Simulated material handling task:
 - A box (6 kg, 37 cm * 33 cm * 26 cm).
 - A working platform (4 m * 3m * 1m);
 - Repeat the above steps for three times and rest for 5 seconds to start another round.
 - o 10 rounds in total



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Results and discussion

Comparison between different work postures



 Squatting lifting is a better posture for material handling than bending lifting

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 Latency time: 0.5s for each frame on one GTX 1080Ti GPU.

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Study 2: A multicomponent and neurophysiological intervention for the emotional and mental states of high-altitude construction workers 心理疲劳





Research background

Aimed object: High-altitude construction workers (e.g., Scaffolders)

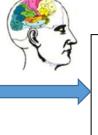
- *Two main accidents:* Falling from height and object strikes *Four requirements:*
- 1. Technical requirements
- 2. Physical requirements
- 3. Regulation requirements



Scaffolders working at height

4. Emotion and mental status requirements——the causal relationships are as below.

Workers' emotional states (e.g., pleasure, displeasure, excitement, and relaxation)



(1)cognitive status (e.g., attention and motivation),

(2) decision making and behaviors (e.g., risk-taking behaviors affecting unsafe actions),(3) mental and physical health (e.g., stress, sleep disorder, and headache)



Work performance, such as safety, health, quality, and productivity





Research method

Step 1: Status simulation

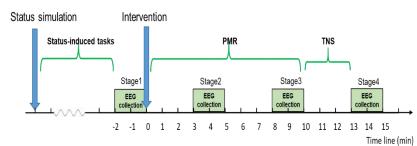
Part 1—— Induce mental fatigue Through a modified stroop color-word interference task (30min)

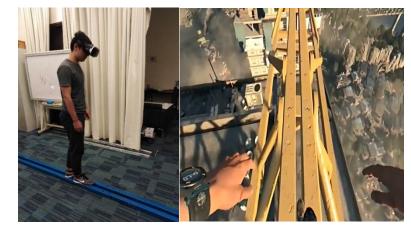
Part 2——Induce certain negative emotions of scaffolders Through a VR mission simulating the high-altitude walk site (10min)



An online stroop test







VR mission simulating the high-altitude walk

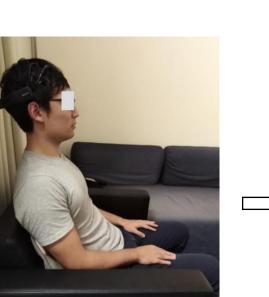
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Step 2: Intervention

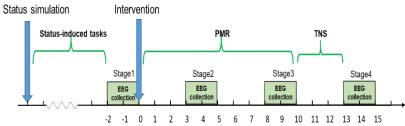
Part 1——Progressive muscle relaxation (PMR) (10min)

Part 2——Trigeminal nerve stimulation (TNS) (3min)



Progressive muscle relaxation in a lounge environment

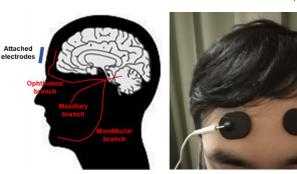
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Time line (min)



The medical and portable external pulse generator



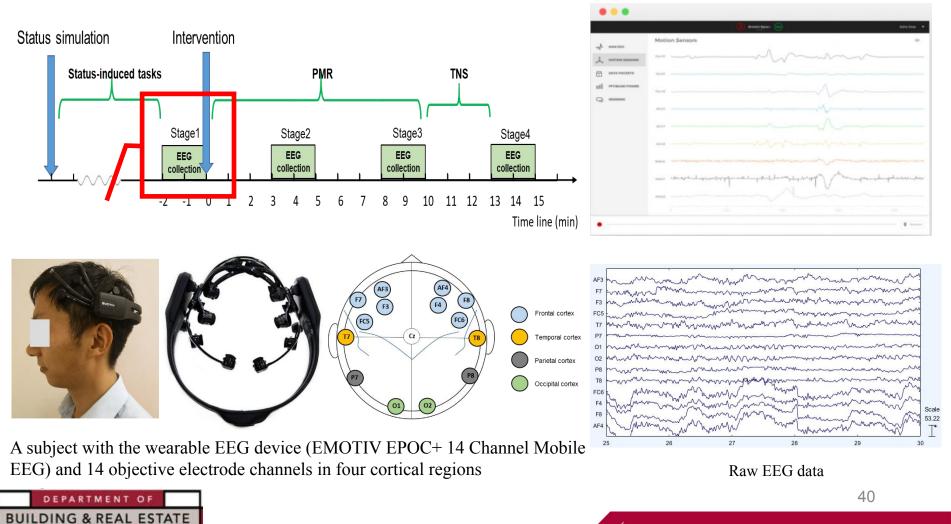
Two adhesive rubber electrodes placed corresponding to the ophthalmic branch of the trigeminal nerve

Waveform	Frequency1 (Hz)	Frequency2 (Hz)	Frequency3 (Hz)	Note
Continuous wave	10	30	50	
Discontinuous wave	10	30	50	3s on/3s off
Disperse-dense wave	10/30	30/40	40/50	2s disperse/4s dense



Research method: Data collection for method evaluation

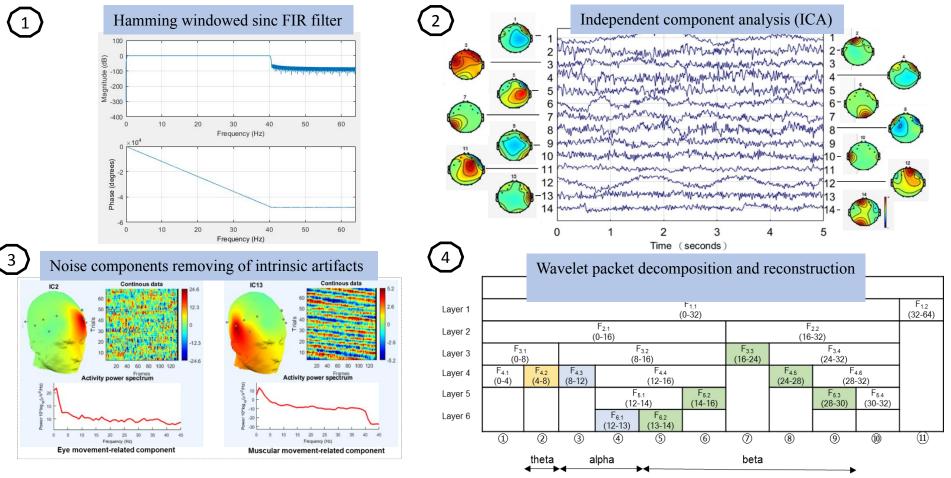
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Research method: Data processing



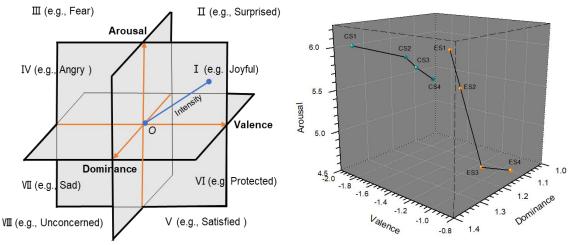


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Results and discussion

Statistical analysis based on processed EEG signals

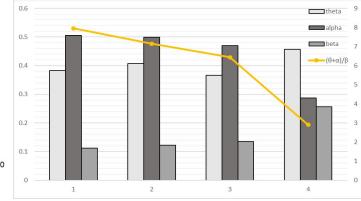


Emotional state regulation

VDA (Valence-Dominance-Arousal) model

After this multicomponent and neurophysiological intervention, the emotional state of high-altitude construction workers tend to be mitigated to **a relatively pleased, autonomous, and excited level.**

Mental fatigue regulation



Trend of mental fatigue adjustment of the experimental group through intervention sessions

The multicomponent and neurophysiological intervention **reduces the mental fatigue** of high-altitude construction workers.

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Study 3: Evaluating the impact of mental fatigue on construction equipment operators' ability to detect hazards using wearable eye-tracking technology 体力疲劳和心理疲劳的相互作用





Evaluating the impact of mental fatigue on construction equipment operators' ability to detect hazards using wearable eye-tracking technology

Research background

- □ Mobile construction equipment and safety
- 50% fatal accidents are related to construction equipment (Marsh and Fosbroke, 2015; OSHA 2018)
- The contact collision between pedestrian workers and equipment accounts for a large portion of construction-equipment-related accident (Shen et al., 2016, CFOI, 2014, Kazan and Usmen, 2018)



□ What caused the accident ?

- Operator's faliure in attention is one of the leading cause (Shapira and Lyachin, 2009, Hinze and Teizer, 2011, Fang and Cho, 2017)
- Mental fatigue can easily lead to poor hazard perception performance of construction equipment operations and accidents in the worst case scenario







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Evaluating the impact of mental fatigue on construction equipment operators' ability to detect hazards using wearable eye-tracking technology

Research method

Participants

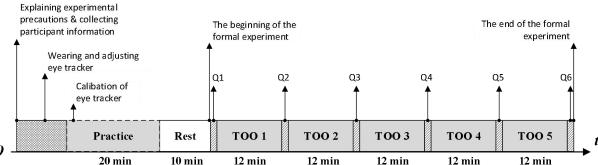
12 males between the ages 24 and 35.

Apparatus and measurement

Wearable eye-tracker and excavator operating simulation system.

Experiment design

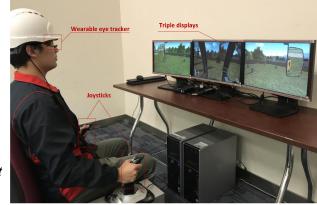
A Time-On-Task procedure considering an excavate-discharge task and a hazard detection task:







Typical simulated experiment situations



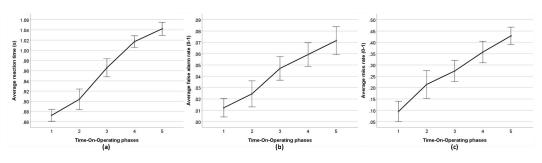




Evaluating the impact of mental fatigue on construction equipment operators' ability to detect hazards using wearable eye-tracking technology

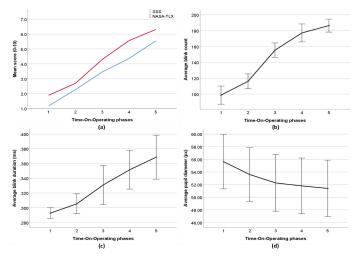
Results and discussion

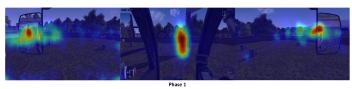
- Operator` hazard detection performance decreased when they experienced mental fatigue
- Operators` hazard detection rate decreased to 70% of the initial performance after 36 min of operating and to 60% after a 60 min task:

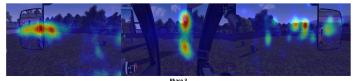


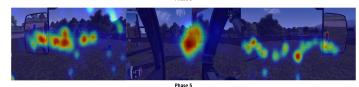
- The findings indicated that the decrement of operators' hazard detection ability results from the changes in his visual attention allocation with increasing mental fatigue
- The feasibility of eye-tracking technology applied to monitor and quantify construction equipment operators` mental fatigue and hazard detection decrement was demonstrated















3. Future Plan



Future project 1: Wearable artificial muscles for reducing the risk of muscle fatigues

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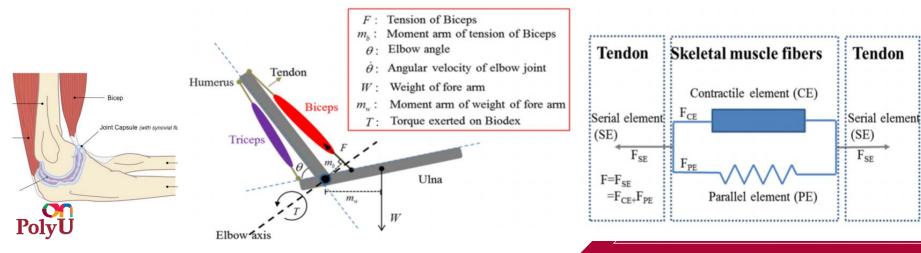
Task 1. Identifying Muscle Capacity Gap

Identifying and modelling of fatigue-prone muscle groups

- Calculating the stress of each muscle group through biomechanical analysis
- Identifying the fatigue-prone muscle fatigue with a muscle fatigue model
- $\circ~$ Calculating and modeling the muscle capacity gap

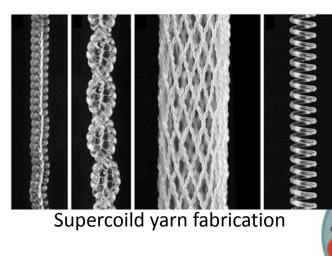


Example model for elbow joint:



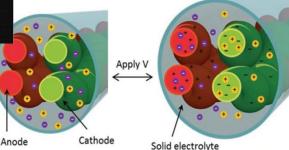
Task 2. Design and fabrication of artificial muscle actuators

- Fabrication of supercoiled fiber/polymer-based artificial muscle actuators
- Synthesize high performance electrolyte to enhance the stroke of actuators
- Produce various electrothermally driven and electrochemically driven actuators



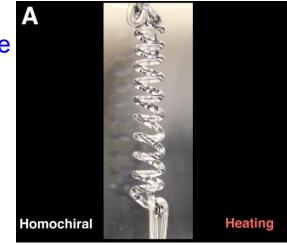


High performance electrolyte



Thermal driven coil polymer fiber actuator

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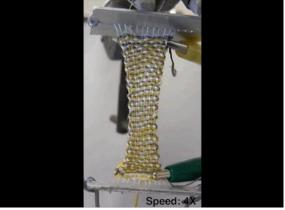
Large current driven actuator



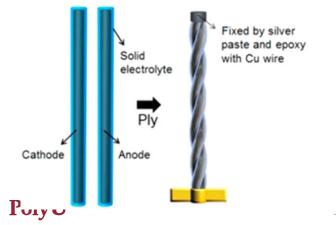


Task 3. Developing Wearable Artificial Muscle Apparati

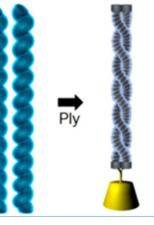
- ***** Optimizing artificial muscle performance to support fatigue-prone muscles Integrate into fabrics
 - Relationship between processing parameter and artificial muscle performance
 - Optimizing performance based on the property of fatigue-prone muscles
 - Encapsulating and Integrating towards wearable 0 devices



Rotational artificial muscle



Tensional artificial muscle



Potential diverse applications

And could be used for miniature medical devices. deployable structures or wearable robotics

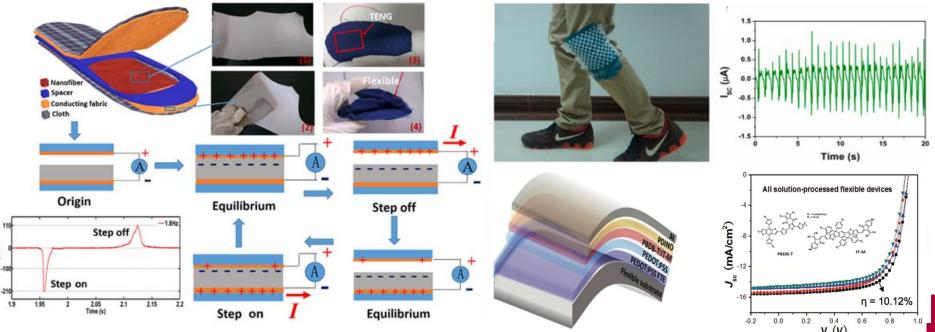


Task 2. Designing green energy harvesting system to power artificial muscles

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- Integrate triboelectric nanogenerators to harvest mechanical energy of works
- o Integrate flexible organic solar cells to gain energy from sunlight exert on works
- Develop power management unit to control sustainable power supply for artificial muscles

Harvesting mechanical and solar energy







Future project 2: Tele-operated and machinery, and robots





A pilot project: construction waste recycling robot for nails and screw (funded by Environment and conservation Fund)

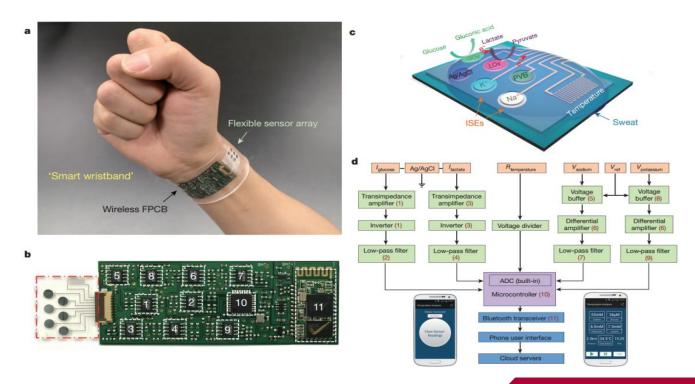
- >Path planning algorithm for complete coverage search
- >Grasping algorithms for robotic hands







Future Project 3: Measurement of physical and mental stress based on psychophysiological measurements





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Ground truth of physical and mental fatigue measures





Portable blood lactate analyzer (Lactate Plus)

Portable saliva based cortisol monitoring system, VerOFy





Conclusions

Construction activities are complex due to interactions between man, machine and material

Site safety is important and it needs hi-tech.









